

# A multisite stochastic precipitation generator based on switching weather states

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## Abstract

Stochastic precipitation generators produce time series of precipitation in a region, of arbitrary length. However, the modeling process should account for a large quantity of zero values. One possible approach is presented, when we model the precipitation occurrence and amounts simultaneously, via a truncated normal distribution. This approach also allows us to fit correlations and lag-1 cross-correlations between the study sites.

# Precipitation generators

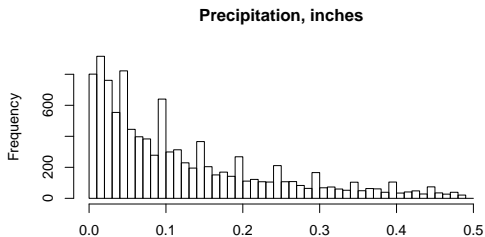
- ▶ ● Get long series of synthetic precipitation
- ▶ ● Statistical properties similar to real precipitation
- ▶ ● Used in hydrologic modeling (water resources, floods, droughts...), agriculture, forestry etc.
- ▶ ● Get some idea of precipitation variability from year to year.
- ▶ ● Climate change?

# Intro

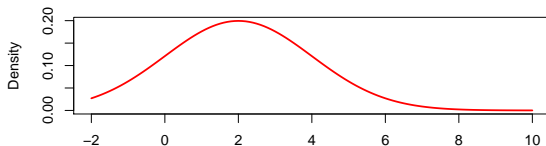
## Precipitation data

- ▶ Multiple variables are observed  $R_{jt}$ , sites (gauges)  $j = 1, \dots, N$ , time  $t = 1, \dots, T$ .
- ▶ A lot of observed values are 0, others are rounded to 0.01 inch.
- ▶ Have to deal with dependencies across time, as long as dependencies between the sites.
- ▶ • Most generators have a separate (discrete) process, modeling occurrence and another one (continuous) modeling amounts. Hard to make them work together.

- ▶ Typical distribution of the precipitation values:



- ▶ Typical picture of the Normal distribution:



# TPT: truncated and power-transformed

Let  $W$  = normally distributed *precipitation potential*

- ▶ Truncated: consider the negative values of  $W$  to lead to zero precipitation
- ▶ Power-transformed: the positive values of  $W$  lead to precipitation  $R = W^\beta$

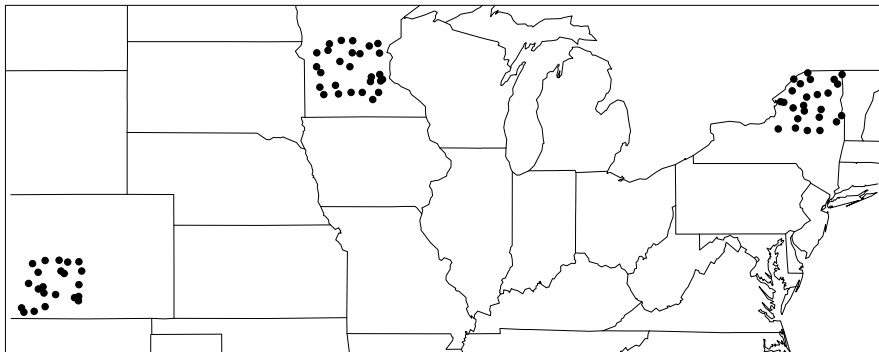
legraphics Lets you fit both the *occurrence* and *amount* of precipitation.  
Parameters:  $\mu$  = mean,  $\sigma$  = st.dev.,  $\beta$  = shape

**Pros:** Multivariate Normal distribution is easy to work with  
(matrices)

**Cons:** “Missing data” whenever  $R < 0$

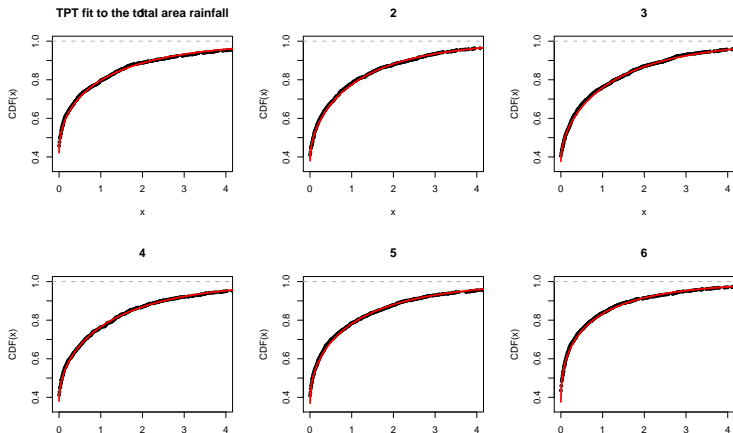
- ▶ Used by Bardossy et al, Sanso et al, ...

# Study areas



# Some fit results

Plotting the CDF (cumulative distribution function = percent of observations below a value): CO daily totals, months 1-6





## Some fit results

- Fits fairly well for each station separately, also for total of all stations,
- Estimate precipitation probability as  $pr = P(W > 0)$ 
  - mean positive:  $pr > 0.5$
  - mean negative:  $pr < 0.5$
- Values of beta between 1.5 and 3.

Seems a good fit for the static model.

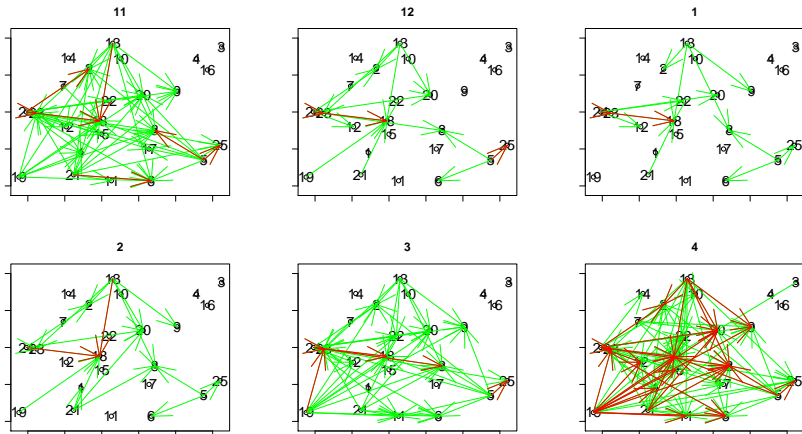
But our model is dynamic: changes with time.

# Spatial dependency

Typically, covariance of precipitation measurements decreases with distance.

# Temporal dependency

Persistency in time: lag-1 correlation (or covariance) of  $R_{jt}$  with  $R_{k,t+1}$  – between sites  $j, k$ .



# Autoregression models

## Scalar autoregression model

persistence at a single site by using

$$W_{t+1} - mean = r(W_t - mean) + noise$$

Values of  $r$  close to 1: very persistent climate,

Values of  $r$  close to 0: “white noise”

## Multivariate autoregression (MAR)

combine all sites in a region, vector  $\mathbf{W}_t$ :

$$\mathbf{W}_{t+1} - mean = \mathbf{r}(\mathbf{W}_t - mean) + \boldsymbol{\xi}_t$$

Matrix-valued  $\mathbf{r}$ , with eigenvalues within unit circle to insure stationarity.

# Multivariate AR

**Goal:** reproduce the lag-1 behavior

Correction: "weather states"  $\mathbf{Z}_t$

$$\begin{cases} \mathbf{Z}_t = \mathbf{r}\mathbf{Z}_{t-1} + \boldsymbol{\xi}_t \\ \mathbf{W}_t = \mathbf{Z}_t + \mathbf{S} + \boldsymbol{\varepsilon}_t, \end{cases} \quad (1)$$

**S:** station effects (means)

elements of  $\boldsymbol{\xi}_t$  are correlated, variance matrix  $\mathbf{V}_\xi$

elements of  $\boldsymbol{\varepsilon}_t$  are white noise

# Multivariate AR

$$\mathbf{Z}_t = \mathbf{r}\mathbf{Z}_{t-1} + \boldsymbol{\xi}_t$$

Number of parameters describing  $\mathbf{r}$  and  $\mathbf{V}_\xi$  is  $N^2 + N(N + 1)/2$ .

On the other hand:

“lag-0” autocovariance of  $\mathbf{Z}$ ,  $\hat{\boldsymbol{\Sigma}}_0$  has  $N(N + 1)/2$  (symmetric matrix)

and lag-1 autocovariance  $\hat{\boldsymbol{\Sigma}}_1$  has  $N^2$  parameters

Thus, if  $\hat{\boldsymbol{\Sigma}}_0$  and  $\hat{\boldsymbol{\Sigma}}_1$  were known (estimated from  $\mathbf{Z}$ 's), we would get:

$$\mathbf{r}^T = \hat{\boldsymbol{\Sigma}}_0^{-1} \hat{\boldsymbol{\Sigma}}_1, \quad \mathbf{V}_\xi = \hat{\boldsymbol{\Sigma}}_0 - \mathbf{r} \hat{\boldsymbol{\Sigma}}_0 \mathbf{r}^T \quad (2)$$

# Fitting the model

Use Markov Chain Monte Carlo, with **Gibbs sampler**

- ▶ Things to estimate:  $\mathbf{r}$ ,  $\mathbf{V}_\xi$ , Station effects,  $\beta$ ,  
 $W_{jt}$ ,  $Z_{jt}$  for all  $j, t \dots \dots$
- ▶ Rename them  $\{X_1, X_2, X_3, \dots, X_d\}$

**Goal:** get  $p(X_1, X_2, X_3, \dots, X_d \mid \mathbf{data})$  - hard!

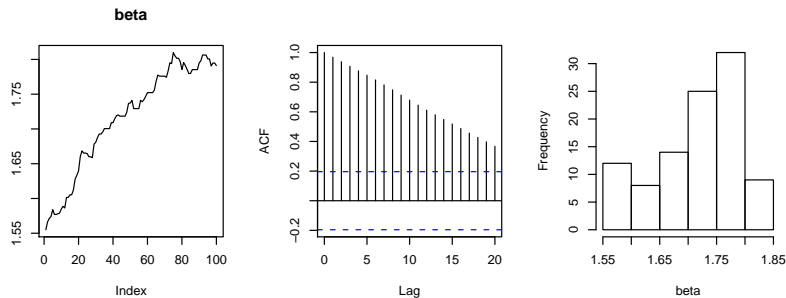
- ▶ **Main idea:** draw a parameter, say  $X_1$  from its *full conditional posterior*  $p(X_1 \mid X_2, X_3, \dots, X_d, \mathbf{data})$ , then draw
- ▶  $X_2$  from  $p(X_2 \mid X_1, X_3, \dots, X_d, \mathbf{data})$
- ▶ .....
- ▶  $X_d$  from  $p(X_d \mid X_1, X_2, \dots, X_{d-1})$

then repeat this procedure over and over again.

# Gibbs sampler

After convergence, get samples from all the parameters to find the means, credible intervals etc.

Example: output for  $\beta$

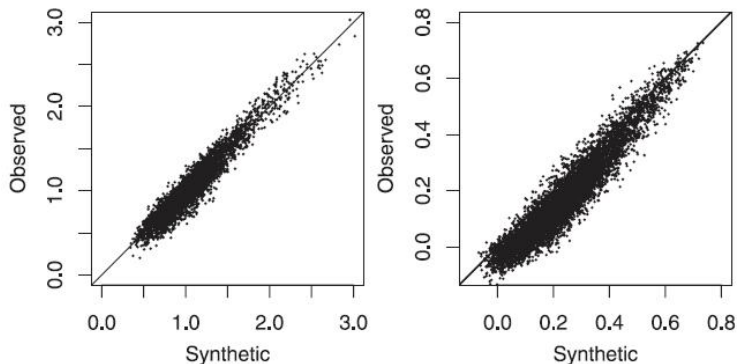




# Gibbs sampler

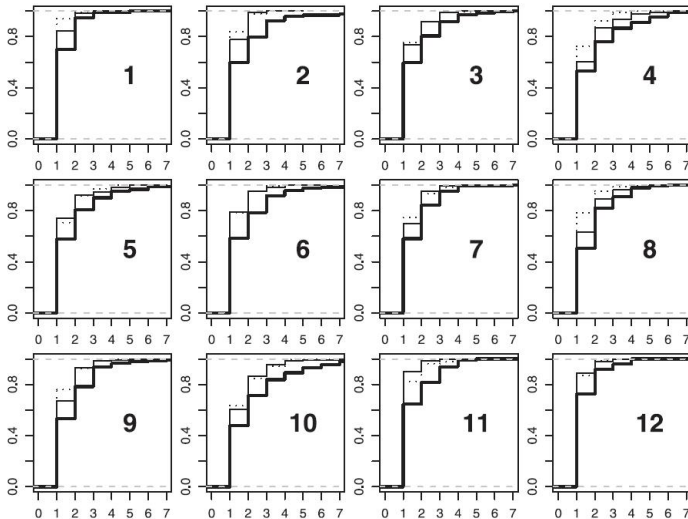
- ▶ Advantages:
  - modular, allows to fully assess variability
  - nice for “missing data” problems
- ▶ Computationally intensive!

# Some results



Comparing observed and synthetic. Left : covariances, right: lag 1 cross-covariances between  $\sqrt{\text{precip}}$  values

Not so great: area-wide dry spell lengths are consistently underestimated



# Conclusion

- ▶ Models complex correlation structure between rainfall observations
- ▶ Allows for wide interannual variability
- ▶ May require tweaking for some data

## **Extensions:**

Weather typing: dry/wet weather, fronts moving etc.

- ▶ From sites to the whole area (gridded)

# Current work: switching weather states

(HMM-like)

Make the parameters in the equation  $\mathbf{Z}_t = \mathbf{r}\mathbf{Z}_{t-1} + \mathbf{S} + \xi_t$  depend on the latent state  $G_t$ , with a finite possible number of states = "weather regimes". For example, dry or wet.

Region-wide latent states would switch according to a Markov Chain.

Simplest version:  $\mathbf{Z}_t = \mathbf{r}\mathbf{Z}_{t-1} + \mathbf{S} + \mu_{G(t)} + \xi_t$

Work in progress

# QUESTIONS?

THANK YOU!

`www.nmt.edu/~olegm/talks/TPT2/` for  
pdf file